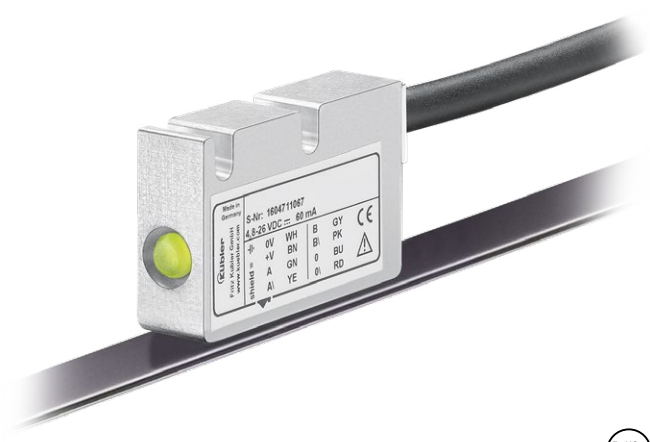
Incremental magnetic measurement system sensor head, magnetic tape

Limes LIM200 / B1 | **Push-pull / RS422**



High flexibility and performance with cost savings.
With a new technology approach based on digital signal processing independent of previous ASIC solutions, Kübler has expanded the range of applications for linear magnetic measurement systems. In conjunction with the available magnetic tapes, the best possible accuracy is now always achieved. Influences due to individual installation and temperature differences during operation are automatically compensated in the sensor head. This facilitates integration into applications and makes the overall system even more powerful.

RoHS

RS422 TTL

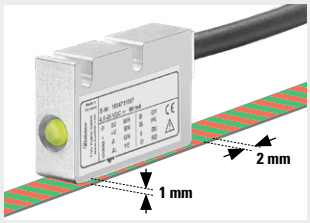
Push-Pull HTL

Features and benefits

- **Highest precision**
  Active offset, phase and amplitude control automatically optimizes the sensor to the current operating situation. Influences due to individual installation and temperature differences during operation are automatically compensated in the sensor head.

- **High flexibility**
  Maximum possible resolution 0.1 µm - freely selectable in 1 nm steps.

- **Optimized for best performance**
  2 mm pole length for high signal quality requirements. This requires a stable installation process that allows an air gap of up to 1 mm.



- **Fast and easy implementation**
  - For use in small installation spaces.
  - Mounting tolerance between magnetic tape and sensor head are compensated by the electronics.
  - Simple adjustment by fastening via slotted holes.
  - Function display via LED.

- **Resistant and robust**
  - Non-contact and wear-free measuring system for a long service life.
  - High shock and vibration resistance.
  - Sturdy housing with degree of protection IP67, optional: Special housing for high resistance to condensation (IP68 / IP69, Resistance to cyclical humidity acc. to EN 60068-2-38 and humidity-heat acc. to EN 60068-2-78).

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Incremental magnetic measurement system sensor head, magnetic tape

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Order code sensor head LIM200

Only in conjunction with magnetic tape B1
Pole lenght 2 mm / distance sensor head–magnetic tape max. 1 mm

8.LIM200	.	X	2	X	A	.	XXXX.XXX	.	XXXX
Type		a	b	c	d		e		f

a *Model*
1 = IP67, standard
2 = IP68 / IP69 and humidity tested acc. to EN 60068-2-38, EN 60068-2-78

b *Reference signal*
2 = with reference signal evaluation [1)]

c *Output circuit / Supply voltage*
1 = RS422 / 4.8 ... 26.4 V DC
2 = Push-pull (HTL/TTL universal) / 4.8 ... 26.4 V DC

d *Type of connection*
A = radial cable, PUR (cable length see **f**)

e *Resolution in µm*
XXXX.XXX µm

Examples of standard resolutions:

0,1 µm =	0000.100 (highest possible resolution)
1 µm =	0001.000
10 µm =	0010.000
25,4 µm (0,001") =	0025.400
2540 µm (0,1") =	2540.000

Further examples:
300 dpi = 25,4 mm/300 = 0,084666 mm

84,6666 µm =	0084.666

Resolution through 4-fold evaluation in following electronics.
(Only in conjunction with magnetic tape B1)

f *Cable length (XXXX =* length in dm*)*
0020 = 2 m [6.56'] (standard)
0030 = 3 m [9.84']
0050 = 5 m [16.40']
0080 = 8 m [26.25'] (only with supply voltage > 6 V)
0100 = 10 m [32.80'] (only with supply voltage > 6 V)
0150 = 15 m [49.21'] (only with supply voltage > 6 V)
0200 = 20 m [65.62'] (only with supply voltage > 6 V)

Order code magnetic tape B1

Only in conjunction with sensor head LIM200
Pole lenght 2 mm / distance sensor head–magnetic tape max. 1 mm

8.B1	.	10	.	010	.	XXXX
Type		a		b		c

a *Width magnetic tape*
10 = 10 mm

b *Version*
010 = without reference track, with masking tape, self-adhesive

c *Tape length (XXXX = Length in dm)*
0010 = 1 m (stock type)
0020 = 2 m (stock type)
0030 = 3 m
0040 = 4 m
0050 = 5 m (stock type)
0060 = 6 m
0070 = 7 m
0080 = 8 m
0090 = 9 m
0100 = 10 m (stock type)
0200 = 20 m
0700 = 70 m

Optional on request
- other lengths up to 70 m
- magnetic tape with reference track
- magnetic tape without masking strip

1) The sensor head always includes the function of evaluating a reference signal (**b** = 2).
In order to provide a reference point as an output signal, a magnetic tape B1 with reference track is required.
For magnetic tapes with a reference track, one signal is detected for each reference point. For full-track magnetic tapes without a reference track, a signal is detected at every second pole.

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Incremental magnetic measurement system sensor head, magnetic tape	Limes LIM200 / B1	Push-pull / RS422

Accessories / displays		Order no.
Codix 560, preset counter 6-digit 	- Counter, tachometer, time counter and position display in one device - Scalable display - Readable via RS232/485 interface or configurable via MODBUS or CR/LF protocol	**6.560.010.XXX** Details s. datasheet
571T touch, multifunction preset counters 8-digit 	- Measuring function for RPM, speed, speed from elapsed time, machine cycle time, throughput time (reciprocal rotary speed), as well as numerous count functions such as position display - Fast counting input (250 kHz/HTL, 1 MHz/RS422) - 4 switching outputs as limit values (response time < 1 ms) - Scalable analog output (response time < 150 ms), resolution 16 bit - Serial interface RS232 or RS485 for reading in and out the data	**6.571T.01X.XXX** Details s. datasheet

Further Kübler accessories can be found at: kuebler.com/accessories
Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

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Incremental magnetic measurement system sensor head, magnetic tape

Limes LIM200 / B1 | **Push-pull / RS422**

Technical data

Mechanical characteristics sensor head

Protection	Model 1 Model 2	IP67 acc. to EN 60529 IP68 / IP69 acc. to EN 60529 and humidity tested acc. to EN 60068-2-38, EN 60068-2-78
Operating temperature		-20 °C ... +80 °C [-4 °F ... +176 °F]
Shock resistance		5000 m/s², 1 ms
Vibration resistance		300 m/s², 10 ... 2000 Hz
Pole lenght		2 mm
Housing (sensor head)		aluminum
Cable		2 m [6.56'] long, PUR 8 x 0.14 mm² [AWG 26], shielded, may be used in trailing cable installations
Status LED	green red	ready for operation Magnetic field error, e.g: - Distance between sensor head and magnetic tape too large - Pole lenght of magnetic ring and sensor head do not match

Magnetic tape B1

Pole length		2 mm
Tape length max.		131 m
Dimensions	width thickness	10 mm 1.97 mm incl. masking tape
Temperature coefficient		16 x 10^{-6}/K
Working temperature		
without adhesive tape		-20 °C ... +80 °C [-4 °F ... +176 °F] [1]
with adhesive tape		-20 °C ... +65 °C [-4 °F ... +149 °F]
Mounting		adhesive joint
Measuring		0.1 m (to receive an optimal result of measurement, the magnetic tape should be ca. 0.1 m longer than the desired measuring length)
Bending radius		≥ 150 mm (when mounted solely with adhesive tape)
Material metal tape		precision steel strip 1.4310 acc. to EN 10088-3

Electrical characteristics

Output circuit		**RS422**	**Push-pull**
Supply voltage		4.8 ... 26.4 VDC	4.8 ... 26.4 VDC
Power consumption (no load)		max. 80 mA	max. 80 mA
Permissible load / channel		120 Ohm	+/- 20 mA
Output frequency max.		300 kHz	100 kHz 300 kHz (for supply voltage ≤ 8 V)
Signal level	HIGH LOW	min. 2.5 V max. 0.5 V	min. +V - 2.0 V max. 0.5 V
Reference signal		For magnetic tapes with a reference track, a reference signal is output for each reference position. For magnetic tapes without a reference track, a reference signal is output at every second pole.	

Accuracy

Magnetic tape	± (0,025 + 0,02 x L) mm up to L_{max} = 70 m / L in [m]	
Sensor head	± 0.01 mm interpolation error accuracy, at T = 20 °C and gap sensor head/magnetic tape 0.4 mm	
Repeat accuracy	±1 increment	
Resolution / Speed		
resolution (4-fold)	speed at output frequency $f_{max.}$ = 100 kHz	speed at output frequency $f_{max.}$ = 300 kHz
0,1 µm	0,04 m/s	0,12 m/s
5,0 µm	2,00 m/s	6,00 m/s
25,0 µm	10,00 m/s	30,00 m/s

Approvals

CE compliant acc. to
EMV-Richtlinie 2014/30/EU
RoHS-Richtlinie 2011/65/EU

Terminal assignment

Output circuit	Type of connection	Cable (insulate unused cores individually before initial start-up)									
1, 2	A	Signal:	0 V	+V	A	$\overline{A}$	B	$\overline{B}$	0	$\overline{0}$	⏚
		Aderfarbe:	WH	BN	GN	YE	GY	PK	BU	RD	shield

+V: Supply voltage sensor +V DC
0 V: Supply voltage sensor ground GND (0 V)
A, $\overline{A}$: Incremental output channel A / cosine signal
B, $\overline{B}$: Incremental output channel B / sine signal
0, $\overline{0}$: Reference signal
⏚: Sensor housing (shield)

1) Magnetic tape (ends) attached by screwing, clamping or equvalent.

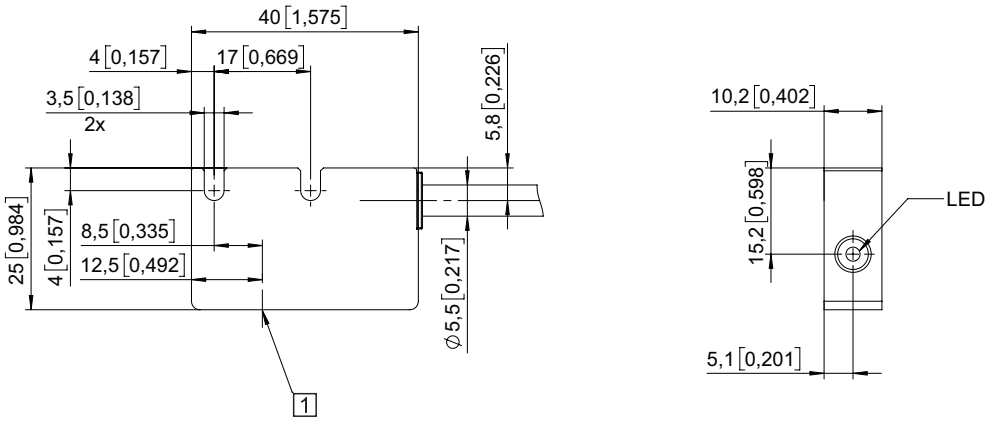
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Incremental magnetic measurement system sensor head, magnetic tape | **Limes LIM200 / B1** | **Push-pull / RS422**

Dimensions

Dimensions in mm [inch]

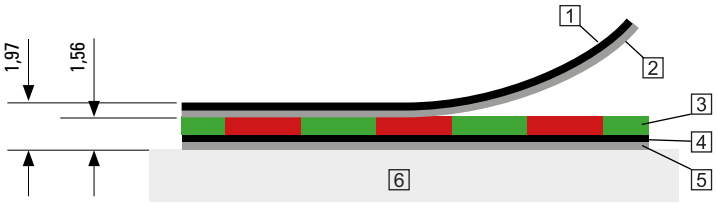
Sensor head



[1] Active measuring area

Magnetic tape B1

[1] Stainless steel cover strip
[2] Double-sided adhesive tape
[3] Magnetized plastic tape
[4] Stainless steel carrier strip
[5] Double-sided adhesive tape
[6] Mounting surface



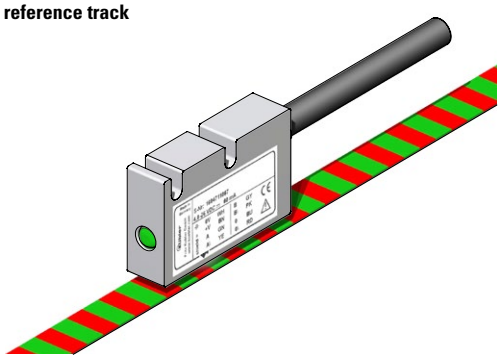
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Incremental magnetic measurement system sensor head, magnetic tape | **Limes LIM200 / B1** | **Push-pull / RS422**

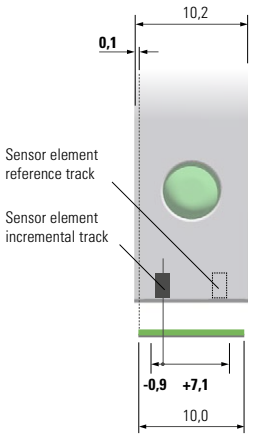
Technology in detail

Permissible mounting tolerances

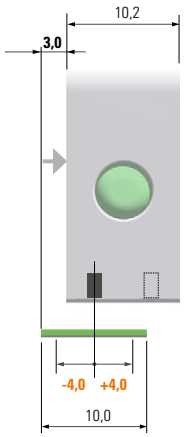
Lateral offset when using a magnetic tape without an additional reference track



When using the sensor without reference signal evaluation, the lateral tolerance of -0.9 mm in one direction is very restricted for operation. By mounting the sensor head offset by 3.0 mm to the magnetic tape, a tolerance range of ±4.0 mm in both directions can be achieved.

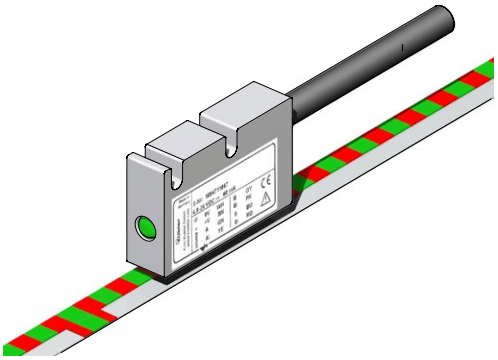


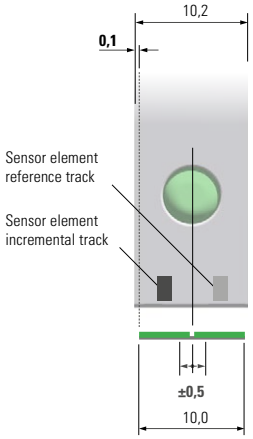
Tolerances for operation -0,9/+7,1 mm



Tolerances for operation -4,0/+4,0 mm

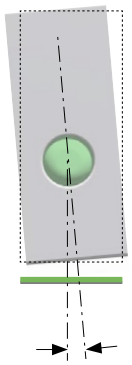
Lateral offset when using a magnetic tape with an additional reference track





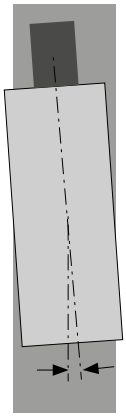
Tolerances for operation -0.5/+0.5 mm

Tilting



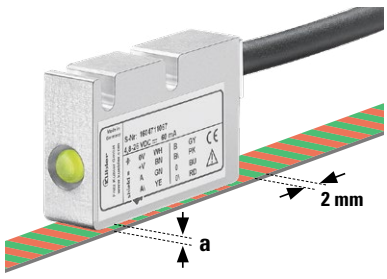
Tolerances for operation ±3°

Torsion



Tolerances for operation ±3°

Distance sensor magnetic tape



a =
Distance sensor head / magnetic tape (pole length 2 mm): 0.1 ... 1.0 mm (0.4 mm recommended)

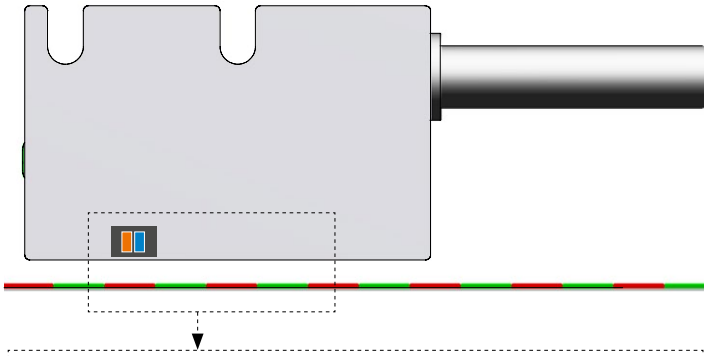
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Incremental magnetic measurement system sensor head, magnetic tape | **Limes LIM200 / B1** | **Push-pull / RS422**

Technology in detail

Functional principle

The sensor element for the incremental track records 2 signal periods, which are offset by 1/4 of the pole length, as input signals A and B.
–> 90° phase shift



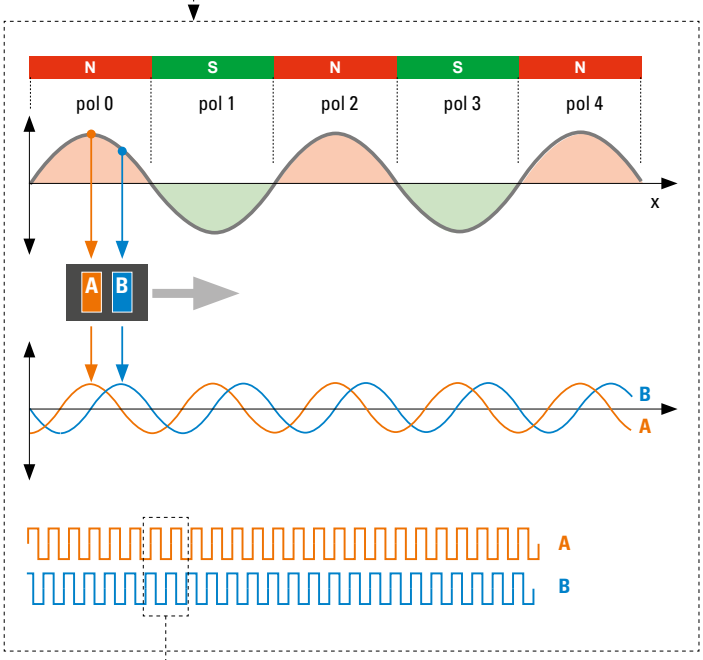
magnetic tape

magnetic field
magn. period = 2 pole lengths

sensor element
incremental track

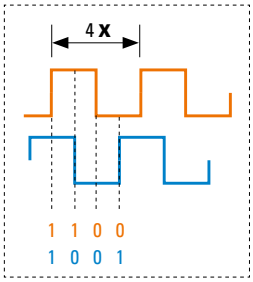
generated voltage
electrical period = 1 pole length

A square wave signal period is calculated from each input signal period, which corresponds to the set resolution



Higher resolution through 4-fold evaluation

The offset of the two square-wave signal periods results in 4 different states of signal A and B per period



Example:

Resolution set in the sensor head = **x**	ex.	0.1 mm
Period of the square wave **A** und **B** signals generated in the sensor head = 4 x resolution	ex.	4 x 0.1 mm = 0.4 mm
The resolution x is achieved by 4-fold evaluation in the electronics downstream of the sensor head	ex.	0.4 mm / 4 = 0.1 mm

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